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Miyake, Y.; Freeman, W.T.; Ohta, J.; Tanaka, K.; Kyuma, K.;
[Lasers and Electro-Optics Society Annual Meeting, 1996. LEOS 96., IEEE](#)
Volume 1, 18-19 Nov. 1996 Page(s):292 - 293 vol.1
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Jhing-Fa Wang;
[Advanced Information Networking and Applications, 2005. AINA 2005. 19th Int](#)
[Conference on](#)
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- ☐ 3. **Real time actions and gestures as intuitive user interface for creative 3D**
Looi, N.K.; Loo, C.K.; Pau, K.N.;
[Active Media Technology, 2005. \(AMT 2005\). Proceedings of the 2005 Interna](#)
[on](#)
19-21 May 2005 Page(s):487 - 490
Digital Object Identifier 10.1109/AMT.2005.1505403
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- ☐ 4. **Virtual reality and telepresence: visual worlds from non-visual sensors**
Stone, R.J.; King, I.; Dalton, G.; Weaver, I.;
[Real World Visualisation - Virtual World - Virtual Reality, IEE Colloquium on](#)
26 Sep 1991 Page(s):3/1 - 3/6
[AbstractPlus](#) | Full Text: [PDF](#)(356 KB) IEE CNF
- ☐ 5. **Coordination of perceptual processes for computer mediated communica**
Coutaz, J.; Berard, F.; Crowley, J.L.;
[Automatic Face and Gesture Recognition, 1996., Proceedings of the Second I](#)
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<u>L6</u>	L5 and tilted	16	<u>L6</u>
<u>L5</u>	(vision or visual) and media and gesture and recognition and movements and position\$ and sensor\$ and print\$ and robot\$ and calibrat\$	56	<u>L5</u>
<u>L4</u>	(vision or visual) and media and gesture and recognition and movements and position\$ and sensor\$ and print\$ and robot\$ and calibration	56	<u>L4</u>
<u>L3</u>	L2 and robot and position\$	2	<u>L3</u>
<u>L2</u>	L1 and print\$	15	<u>L2</u>
<u>L1</u>	scale-invariant near features	32	<u>L1</u>

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<u>L2</u>	L1 and finger	32	<u>L2</u>
<u>L1</u>	(vision or visual) near based and media and gesture and recognition and movements and position and sensor\$	56	<u>L1</u>

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